

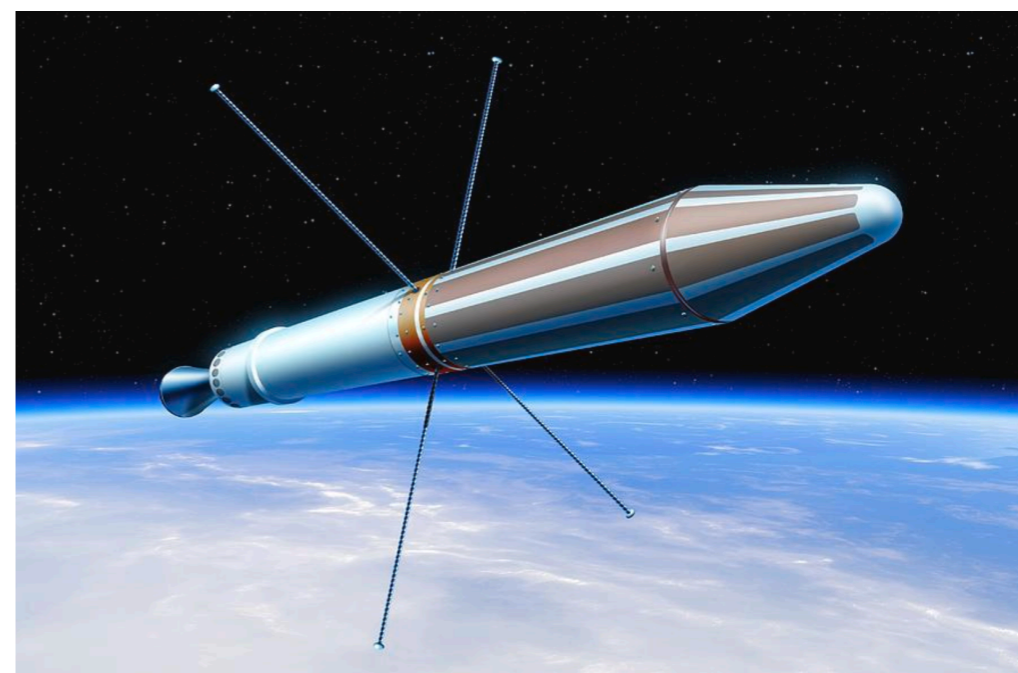
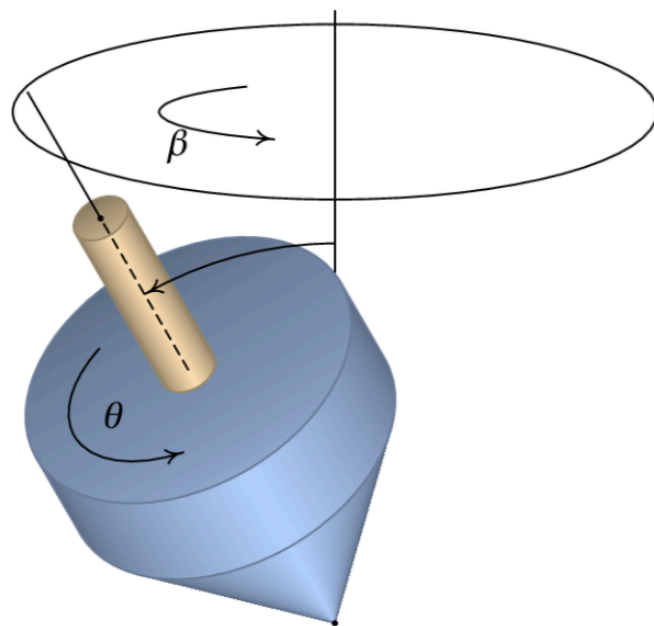
April 14, 2020

$F=ma$

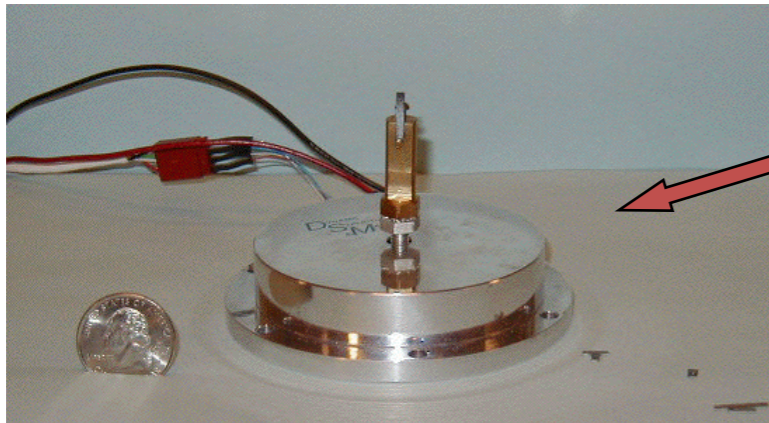
In an inertial frame of reference, the vector sum of the forces \vec{F} on an object is equal to the mass m of that object multiplied by the acceleration \vec{a} of the object: $\vec{F} = m\vec{a}$.

In their original form, Newton's laws of motion are not adequate to characterize the motion of rigid bodies and deformable bodies. Leonhard Euler in 1750 introduced a generalization of Newton's laws of motion for rigid bodies called *Euler's laws of motion*.

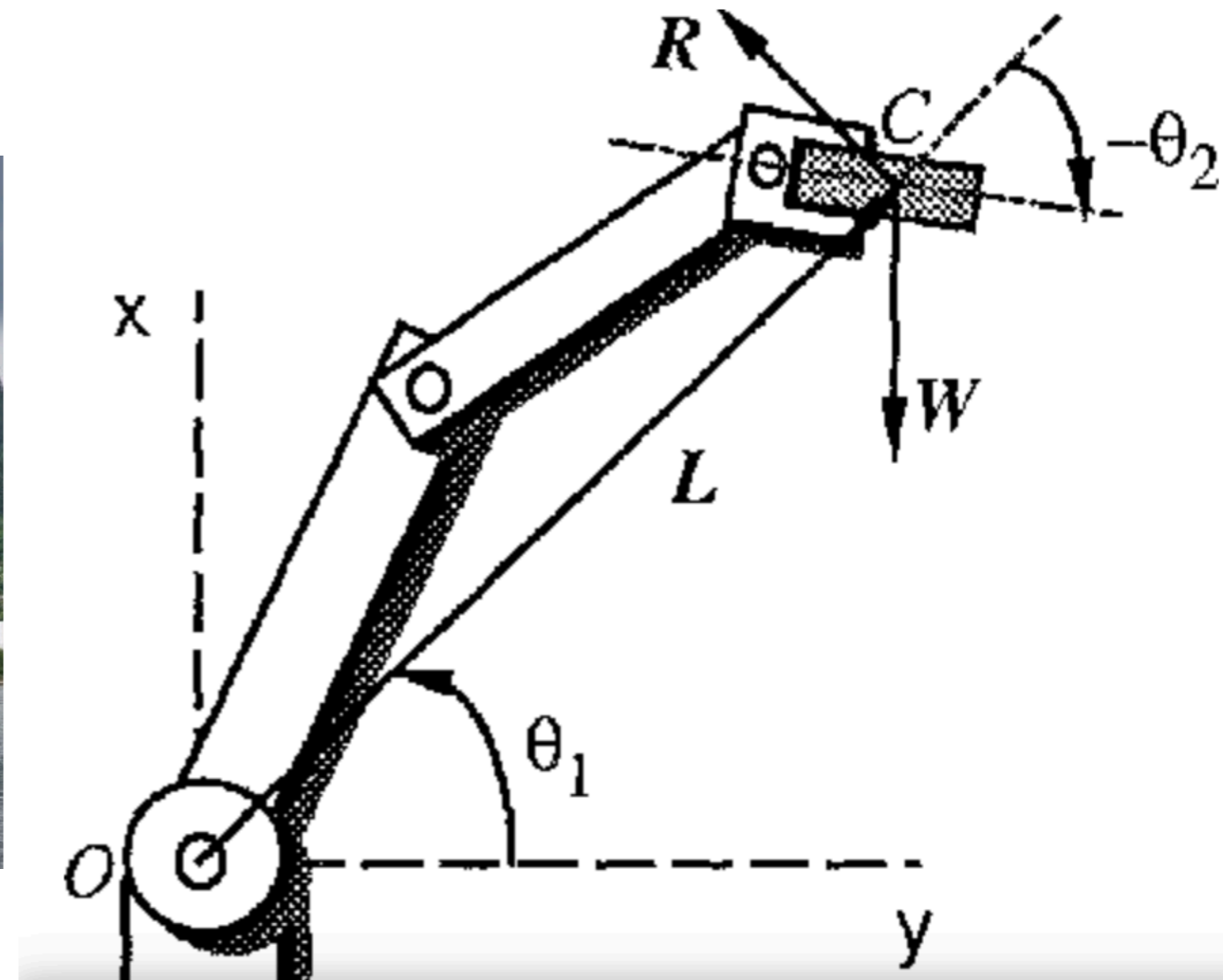
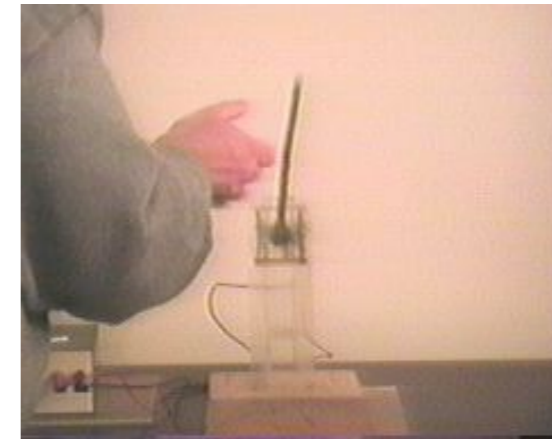
—<https://en.wikipedia.org/>



Time constants, mass, and inertia come important

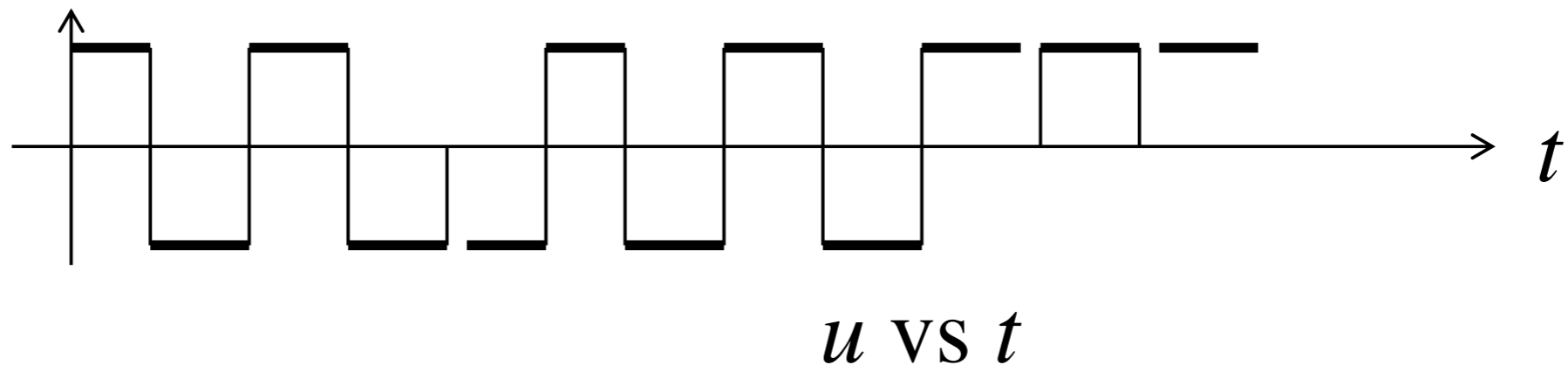
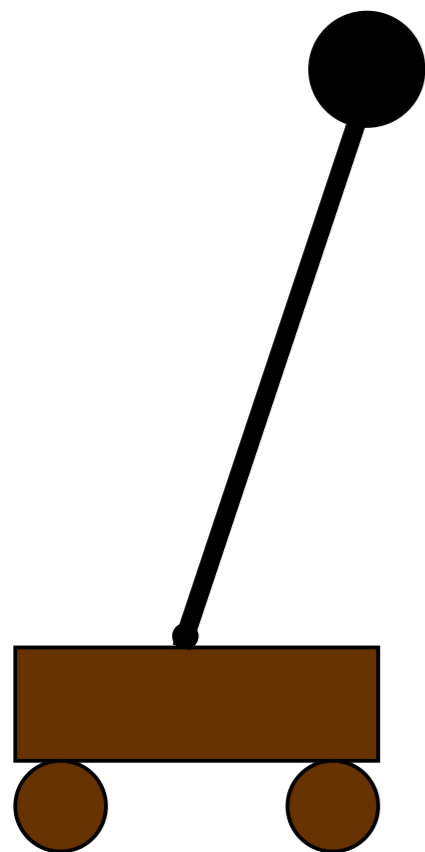


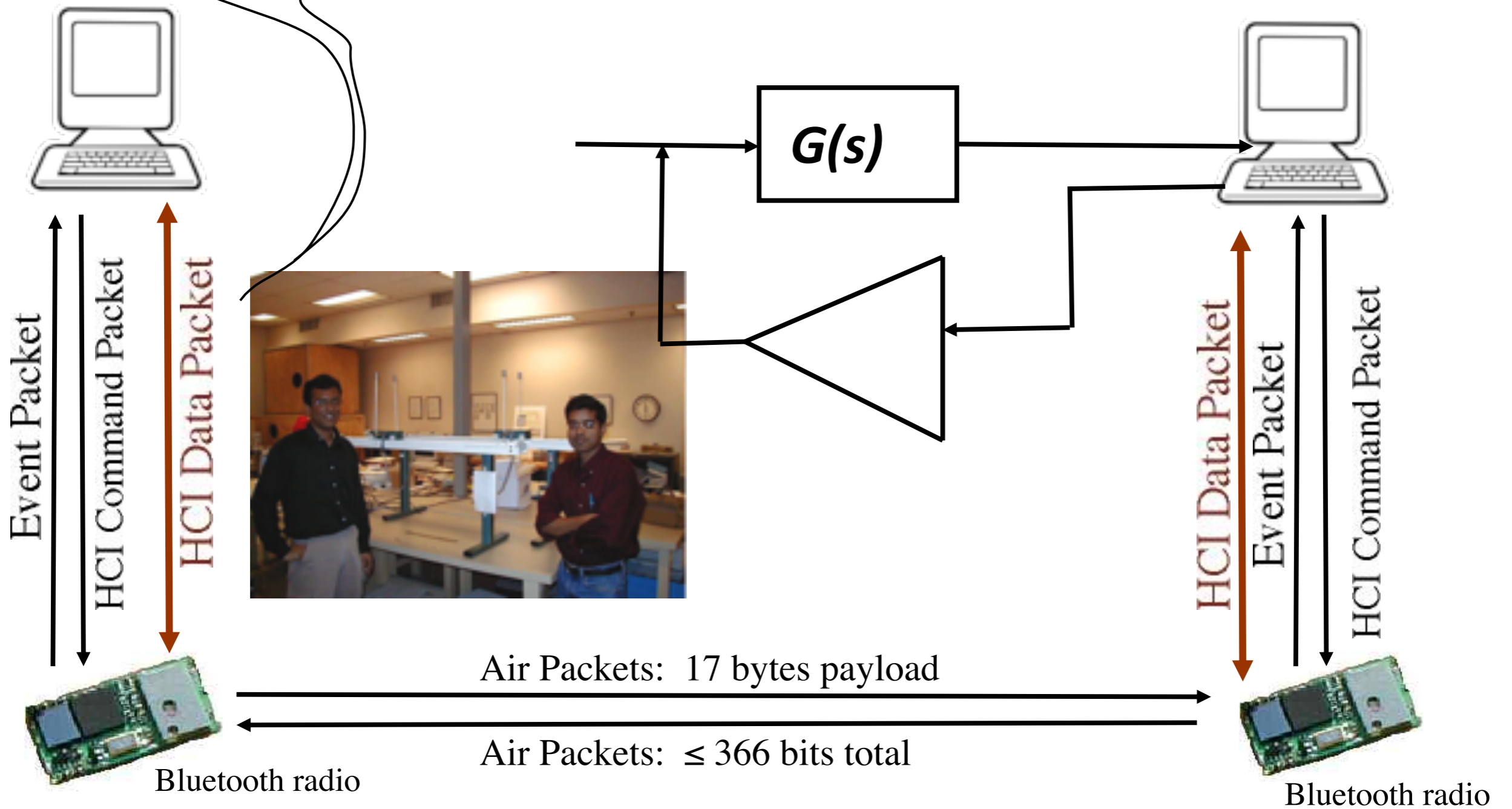
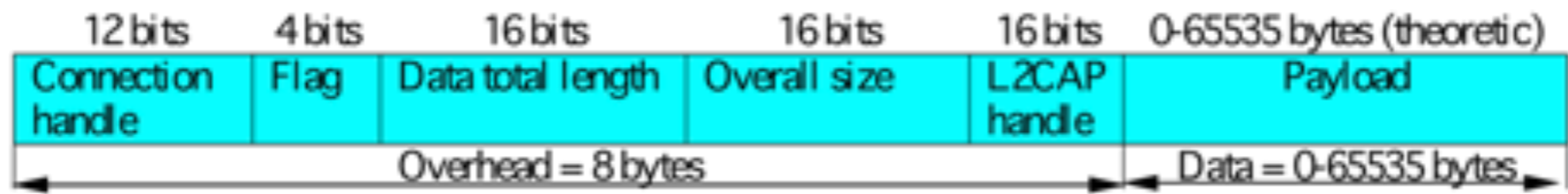
The world's smallest inverted pendulum--- stabilized by vertical oscillation of the base.



Suppose there are only two (finitely many) actions that can be taken:

- Jerk the cart left or right one centimeter
- Under what circumstances can one keep the pendulum upright using this very coarse type of “control?”
- Ans: If and only if there is a sufficiently high **actiel** rate.

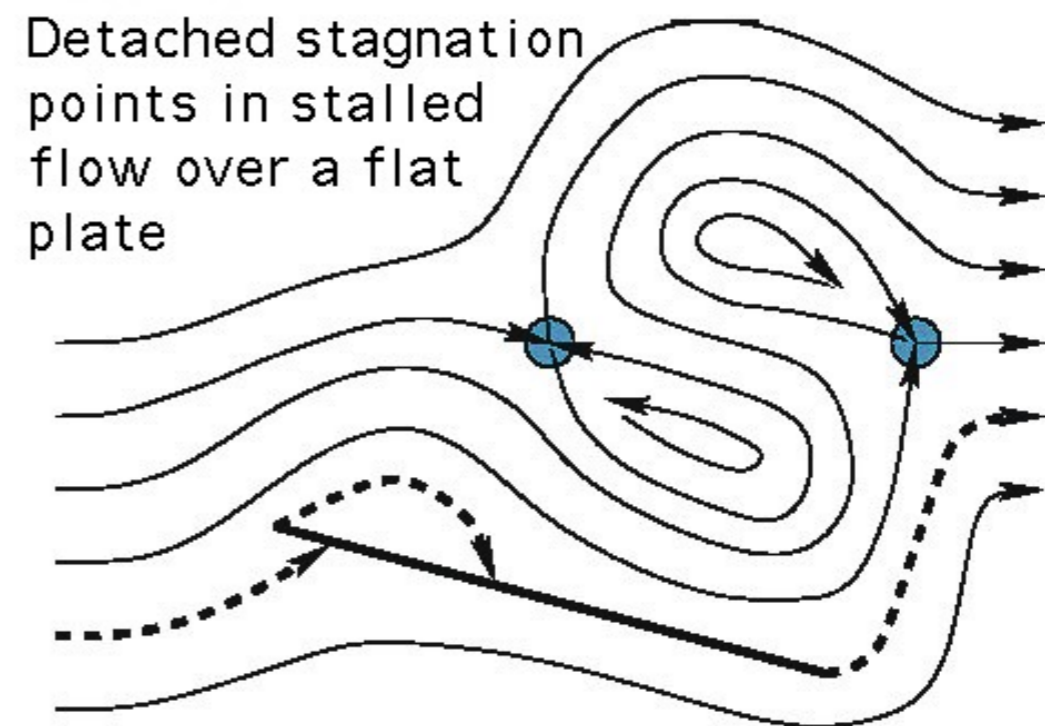
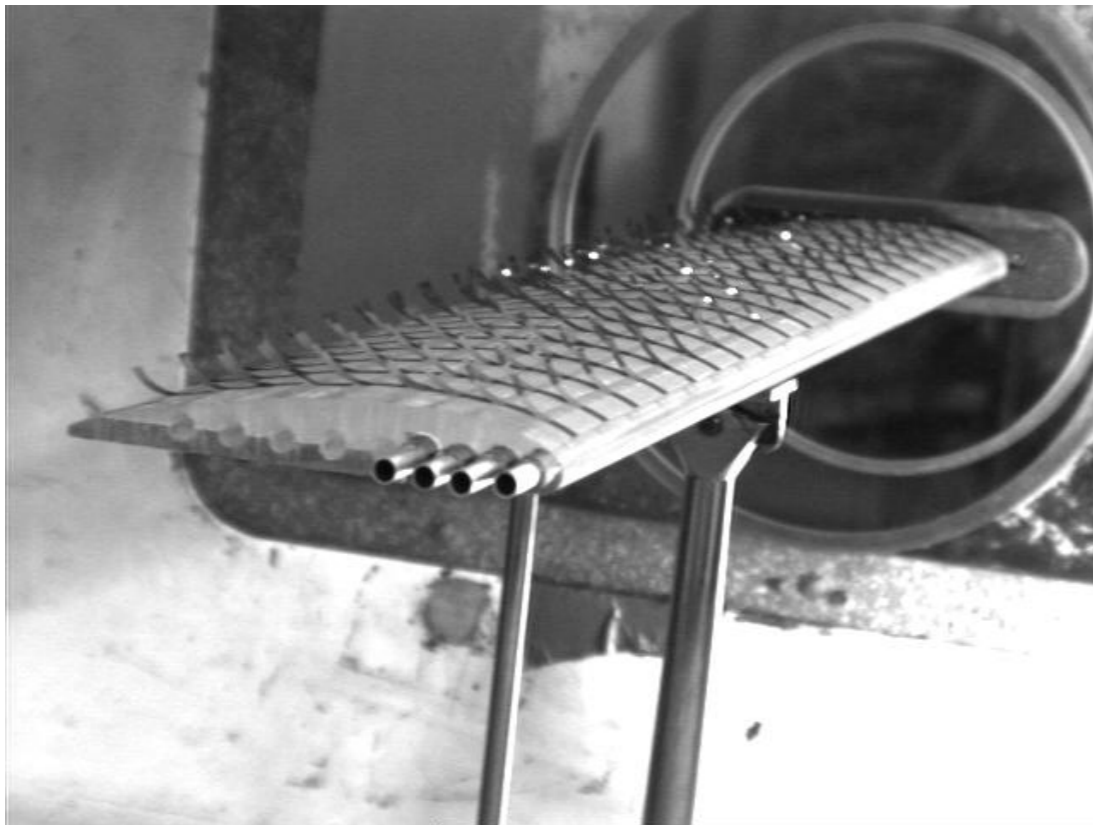




Distributed and asynchronous control under communication constraints

Key Problem:

- Combined control and data-compression



Control of boundary flow using distributed arrays of micro-jet actuators is one target application for use of communicating sensor/actuator networks.

Housekeeping

- **Three people still need to sign up for presentation slots.**
- **Homework 6 is posted.**
- **Shout-out to Joanna Thelen**

<http://www.bu.edu/articles/2020/introducing-dart-a-robot-inspired-by-creatures-in-netflixs-stranger-things/>